Interrupts

CPTS 260
Synchronization

- If processor issues instructions too rapidly, the results can be unpredictable.
- We can prevent such problems via synchronization.
- Processor operates faster than an I/O Device, programmed I/O requires the processor to synchronize with the device that is being controlled.
Polling

- Basic form of synchronization.
- Requires the processor to ask the device whether the operation has been completed before sending next operation.
- Advantage of Programmed I/O devices: inexpensive.
- Disadvantage of Programmed I/O devices: Computational Overhead.
Interrupt Driven I/O

- I/O Device Hardware: Operate independently from the control of a processor.
- Bus Architecture: Bus must support two way communication between processor and device.
- Processor Architecture: Process to stop normal program temporarily and handle the device.
- Programming Paradigm: Synchronous and Asynchronous style!
Definition

- Event that disrupts the normal execution of a program and causes the execution of special instructions
An interrupt is any service request that causes the CPU to stop its current execution stream and to execute an instruction stream that services the interrupt.

When the CPU finishes servicing the interrupt, it returns to the original execution stream at the point where it left off.
INTERRUPTS CAN BE REQUESTED FROM ANY OF THE FOLLOWING SOURCES:

- Hardware driven (Focus on this)
- Software interrupts (programmed interrupt requests (PIRs))

A program using interrupts is usually structured as follows:

```assembly
.data
theString: .space 64 .text
main: li $v0, 8
la $a0, theString
li $a1, 64
syscall
jr $ra
```

Exceptions, such as page faults
Interrupts & Fetch-Execution

- Repeat Forever{
  - **Test:** If any device has requested interrupt, handle and then continue with next iteration.

  **Fetch:** Access the next step of the program from the location where the program is stored.

  **Execute:** Perform the next step of the program
Interrupt Request (IRQ)

- An interrupt is a signal from one part of the computer to the processor indicating that a service or special action be taken that only the CPU can perform.
- When a device needs the CPU to perform a task, transfer data from memory, issue an I/O, etc., it signals the CPU using its IRQ line.
- Each device is assigned a specific IRQ number so that the processor knows the device to which it needs to respond.
Interrupt requests are sent to a special system component, called an interrupt controller.

The interrupt controller receives and verifies requests and passes them on to the processor.
Handling An Interrupt

• Save the current execution state.
• Determine which device interrupted.
• Call the procedure that handles the device.
• Clear the interrupt signal on the bus.
• Restore the current execution state.
Interrupts: Overview

- Complex hardware setup
- Needed for multitasking/multiprogramming OS
Interrupts: An example

\[ \text{Far.} = (\text{cent} \times \frac{9}{5}) + 32 \]

Program:
- `mov R1, cent`
- `mul R1, 9`
- `div R1, 5`
- `add R1, 32`
- `mov fahr, R1`
Interrupts

Interrupt 

Interrupt Service Routine

mov R1, 0x90  |  mov sensor, R1  |  ret

Program

mov R1, cent

Program

mul R1, 9

time t
Interrupts

Interrupt

Program
mov R1, cent

Save Context

Interrupt Service Routine

Restore Context

Program
mul R1, 9

time t
Interrupts

Program
mov R1, cent
Interrupt
Save Context
eg push R1
Interrupt Service Routine
Restore Context
eg pop R1
Program
mul R1, 9

Time t
When an Interrupt Occurs

- Finish the current instruction
- Save minimal state information on stack
- Transfer to the interrupt handler, also known as the interrupt service routine (ISR)

But there is more to it than this... How do we know which device interrupted?

And what happens if two (or more) devices request an interrupt at the same time?
Control & Status Registers

- They are set of addresses a device uses.
- Control Register: Corresponds to a contiguous set of addresses that respond to a store operation.
- Status Register: Corresponds to a contiguous set of addresses that respond to a fetch.
Interrupt Response Time

Interrupt Response Time = Interrupt Latency + Time in Interrupt Routine
Advantages of Interrupts

- I/O is important aspect for communicating.
- Interrupt driven I/O automatically overlaps computation and the programmer need not take any special action.
- Interrupt adapts to the processor speed and I/O device automatically. (Never underestimate or overestimate).
An interrupt is any service request that causes the CPU to stop its current execution stream and to execute an instruction stream that services the interrupt.

When the CPU finishes servicing the interrupt, it returns to the original execution stream at the point where it left off.